

16. (New) A remotely controlled vehicle system, comprising:

a remote control signal transmitter for transmitting control signals;

a master model vehicle containing a remote control signal receiver, wherein said master model vehicle is controlled by said control signals as it travels along a first pathway; and

plurality of slave model vehicles that are coupled to said master model vehicle and to each other by at least one linkage element, wherein at least one said plurality of slave models is propelled by said master model vehicle in a pathway outside of said first pathway.

17. (New) The system according to Claim 16, wherein said at least one linkage element causes all of said slave model vehicles to change position relative said master model vehicle when one of said slave model vehicle changes position relative said master vehicle.

18. (New) The system according to Claim 16, wherein a single linkage element with two opposing ends is provided, said linkage element having at least two slave vehicles attached thereto, wherein said linkage element is pivotably connected to said master vehicle so that said linkage positions said at least two slave vehicles on opposite sides of said master vehicle.

19. (New) The system according to Claim 16, wherein said master model vehicle contains a servo motor that is controlled by said remote control transmitter that selectively moves said at least one linkage element.